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#include <iostream>
#include <cstdlib>
#include <ctime>

using std::cout;
using std::cerr;

class Map {
protected:
    int *data;
    int width;
    int height;
    int offset;

    int countHotspots();
    int findHotspotPosition(const int hotspotID);
    void drawLine(const int position, const int direction);
    void drawBorder();
    void generateHotspots();
    void sanitizeHotspots();

public:
    void print();
    void generate(const int pillarCount);
    bool init(const int width, const int height, const int offset);
    void deinit();
    Map(){ data = NULL; width = 0; height = 0; }
    ~Map() { deinit(); }
};

int main(int argc, char *argv[]) {
    srand(unsigned(time(NULL)));

    Map map;
    if (not map.init(61, 28, 2)) return 1;

    map.generate(4);
    map.print();

    return 0;
}

int Map::countHotspots() {
    int cnt = 0;

    for (int y = offset + 1; y < height - 1; y += (offset + 1)) {
        for (int x = offset + 1; x < width - 1; x += (offset + 1)) {
            if (data[y * width + x] == 2) cnt++;
        }
    }

    return cnt;
}

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int Map::findHotspotPosition(const int hotspotID) {
    int cnt = 0;

    for (int y = offset + 1; y < height - 1; y += (offset + 1)) {
        for (int x = offset + 1; x < width - 1; x += (offset + 1)) {
            if (data[y * width + x] == 2) {
                if (cnt == hotspotID) return y * width + x;
                else cnt++;
            }
        }
    }

    return 0;
}

void Map::drawLine(const int position, const int direction) {
    int pos = position;

    while (data[pos] != 1) {
        data[pos] = 1;

        if (direction == 0) pos -= width; // UP
        else if (direction == 1) pos -= 1; // LEFT
        else if (direction == 2) pos += width; // DOWN
        else if (direction == 3) pos += 1; // RIGHT
    }
}

void Map::drawBorder() {
    for (int y = 0; y < height; y++) {
        data[y * width] = 1;
        data[y * width + width - 1] = 1;
    }

    for (int x = 0; x < width; x++) {
        data[x] = 1;
        data[(height - 1) * width + x] = 1;
    }
}

void Map::generateHotspots() {
    for (int y = 0; y < height; y += (offset + 1)) {
        for (int x = 0; x < width; x += (offset + 1)) {
            data[y * width + x] = 2;
        }
    }
}

void Map::sanitizeHotspots() {
    for (int y = 0; y < height; y += (offset + 1)) {
        for (int x = 0; x < width; x += (offset + 1)) {
            if (data[y * width + x] == 2) {
                data[y * width + x] = 1;
            }
        }
    }
}

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void Map::print() {
    for (int y = 0; y < height; y++) {
        for (int x = 0; x < width; x++) {
            int value = data[y * width + x];
            if (value == 0) cout << " ";
            else if (value == 1) cout << "#";
            else if (value == 2) cout << ".";
            else cout << "?";
        }
        cout << "\n";
    }
}

void Map::generate(const int pillarCount) {
    int hotspots = countHotspots();
    while (hotspots > pillarCount) {
        int randHotspotID = rand() % hotspots;
        int direction = rand() % 4;
        int position = findHotspotPosition(randHotspotID);

        drawLine(position, direction);
        hotspots = countHotspots();
    }

    sanitizeHotspots();
}

bool Map::init(const int width, const int height, const int offset) {
    if (((width - 1) % (offset + 1)) != 0) {
        cerr << "ERROR: Bad width\n";
        return false;
    }
    if (((height - 1) % (offset + 1)) != 0) {
        cerr << "ERROR: Bad height\n";
        return false;
    }

    Map::width = width;
    Map::height = height;
    Map::offset = offset;

    data = new int[width * height];
    if (data == NULL) return false;

    for (int i = 0; i < width * height; i++) data[i] = 0;

    generateHotspots();
    drawBorder();

    return true;
}

void Map::deinit() {
    if (data != NULL) {
        delete[] data;
        data = NULL;
    }
}

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